

Power Sharing Using Droop Control for Distributed Generators in DC Micro grid

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Abstract: The power sharing control method is a preferred way for integrating many renewable energy sources into the grid and maintaining their synchronized functioning. Power sharing control between dispersed generators are essential for the reliable operation of the power grid network. In the proposed approach, a DC microgrid's power from each individual generator is shared using a droop control technique. The primary problems with poor current sharing and droop characterize the traditional droop approach. Circulating current issue will also arise due to mismatch in the converters output voltages. The droop index (DI), a measure of merit, is introduced in this study, in order to enhance the efficiency of a DC microgrid. The proposed power sharing control approach can be broadly used to grid-connected networks and island power grid networks in order to achieve high distribution efficiency and stability. The suggested approach also guarantees voltage stability in a DC microgrid. In a MATLAB/Simulink, the power sharing control mechanism is created, modelled, and confirmed.

Key Word: Power sharing; Droop control; Microgrid

1. Introduction

In the modern age, renewable energy use has increased due to growing environmental concerns and rising fossil fuel prices. The need for integrated grid systems powered by renewable resources has increased as a result of the burden that continuous growth in the industrial and commercial sector has placed on the traditional electricity grid. Historically, alternating current has been used because it can change voltage to match needs at the load end. In the sector of electric power generation, transmission, and distribution, the use of DC power has considerably expanded recently. Depending on the availability of power supply, microgrids can operate in grid-connected or off-grid linked modes.

Significant developments in the field of DC energy have led to the adoption of DC microgrids into the electrical grid. For electronics-based appliances, the DC microgrid is suitable and effective [1], [2]. The idea of microgrids is presented in order to integrate renewable energy sources, such as solar, wind, and other sources, with energy storage devices and AC utility lines [3]-[6].

The output power of renewable energy sources (RESs) is variable, unpredictable, and sporadic. Energy storage devices are consequently viewed as a crucial component of DC microgrids in order to overcome these problems. Power converters that act in accordance with particular control approaches are used to link the majority of the microgrid's components to the bus, ensuring the microgrid's steady and efficient operation [7]-[10]. For microgrids, energy from renewable sources is often the main energy source. Droop control is used to regulate and control the voltage by the converters and generators connected to the microgrid. Energy may be transferred more reliably and effectively thanks to DC microgrids, as evidenced by their use [11]-[15]. Depending on the type, microgrids can run independently or be connected to the grid, whether it be AC or DC, of power. DC energy has made tremendous progress, which has resulted in the DC microgrids are being introduced into the power network. The efficiency of the DC microgrids is higher, as well as adherent to the customer's electronic loads [1]. The microgrid often utilizes as their primary source of energy, renewable energy. Voltage is controlled using droop control and control in the microgrid-connected converters and generators. AC microgrids are used has demonstrated to offer improved efficiency and trustworthy energy transfer [3].

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DC distribution is used in system's harmonic management and synchronization have contributed to its widespread adoption [2]. The Integrating the network with the primary power grid ensures its dependability. Given that there is possible for the integration of the electronic AC-DC and DC-AC converters, microgrid alongside the conventional AC grid. The data and telecom industries have seen extensive use of the DC microgrid. Industry, whose independent work nature necessitates an islanded or individual grid system [4,5]. Installation of microgrids can be relied on by regions that are disconnected from the main grid to provide access to the primary grid would be careless. Microgrids on islands can be constructed using their own power. Resource and does not require grid integration. Microgrids generate their own power. This guarantees constant power reliability by using a backup storage system.

To solve this weakness of the AC microgrid, the DC microgrid was created. In addition, it offers advantages in terms of issues with power quality, reactive power control, skin effect, and frequency synchronization. The key issues in the DC microgrid are minimizing voltage regulation across linked loads with reference to bus voltage and equalizing per-unit current sharing among converters. Droop control is a popular method for balancing current sharing among converters, similar to how reactive power sharing is done in the AC microgrid [16]-

[19]. Conventional droop control functions by creating a virtual resistance in lines [20] and [21] to equalize current sharing. However, a further voltage drop lowers the reference bus voltage, which leads to poor voltage regulation. When deciding on the value of virtual resistance, there are trade-offs between voltage regulation and current sharing. Poor low virtual resistance results in current sharing, but better voltage regulation. However, the large value of virtual resistance results in higher current sharing and poor voltage management. A voltage-shifting term and a moderate amount of virtual resistance are added to the reference bus voltage in order to maintain equal current sharing and retain low-voltage regulation. Uneven line resistances are another problem that impairs both current sharing and voltage regulation. These issues are addressed by the adaptive virtual resistance idea. The fixed virtual resistance is subtracted from the output current after it has been multiplied by the current error term. This adaptive resistance drop fluctuates depending on how much the output current deviates from the average output current of all converters. As a result, the present sharing is more precise. Voltage control is still a big problem. This issue is resolved by subtracting the adaptive virtual resistance drop from the bus reference voltage in order to produce a voltage-shifting term. To distribute electricity and reduce circulating current, this article suggests an adaptive droop control approach. As a result, the article's main contribution is to reduce the amount of circulating current in the parallel-

connected DC boost converter. Additionally, regulate voltage and share power in the DC microgrid. The then-current power-sharing methods used in DC distribution systems were discussed. This chapter introduces the building of a new droop controller network, as well as their role in control and power sharing, with a focus on DC systems. AC networks were the context for the invention of droop. The system's voltage is maintained at its rated level using control [29]. The system's operation is sustained by keeping the voltage constant for control and power distribution. Power sharing between the generators is efficiently managed by the controller for each generator. Converter. The DC-DC converters serve as each generator's power sharing interface. The load has a grid connection. Power sharing has a more significant impact on system stability. The critical impacts of instability occurring at each point in this model are intended to be withstood. Generator-conversion apparatus.

The rest of the paper is arranged as follows: Section II briefly about the structure of a DC microgrid system with different source of power. In Section III, the control methodology of the proposed system is discussed. The simulation implementation part and analysis of results is carried out is discussed in Section

2. Structure of DC Micro Grid

The architecture of load sharing between different renewable energy sources has shown in Fig. 1. In the proposed method more than one distributed generators (DGs) are connected to a single microgrid to meet the demand at the load end of the microgrid. The traditional grid network can also be linked with the microgrid. It blends the grid resilience and energy management to increase conversion efficiency. When there is greater availability to power, transmission grid efficiency in the case of DC distributed generators, which require a DC-DC or DC-AC converter system to be integrated with the DC or AC grid is found to be more balanced. DC microgrid systems powered by photovoltaic and wind energy have experienced significant progress in recent years electrical engineering. It introduced power converters that can run exclusively on DC power. The load power demand is also exceedingly increasing for DC source. A DC-DC For DC sources, the load power demand is also extremely high. A DC-DC, As depicted in Fig. 2, a converter has been used as an interface between the power source and the load or grid system. To ensure the system is properly stable, the converter is connected to the external grid or the output load via a coupling resistor. Based on the power demand at the end of the load system, the designed system can be run at any load percentage. The voltage droop should be less than 4%, which is the basis on which the aforementioned model was created.

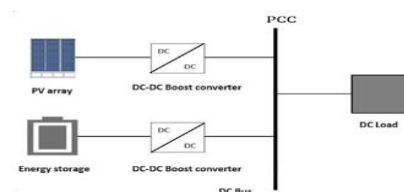


Fig.1 Structure of DC Micro grid

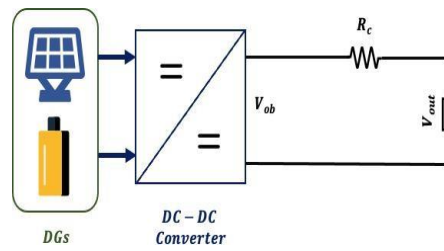


Fig.2: Circuit Model of DC Microgrid

3. Control methodology

This section goes into more detail about the suggested control methods. A DC-DC converter links the solar source and the load, or grid system. The converter is coupled with either the output load or the external grid via a resistor to guarantee that the system is adequately stable. The planned system can be operated at any load percentage depending on the power need at the system's load end. Since the voltage is constantly maintained constant, this is accomplished by managing the current necessary to satisfy the given power demand. In this section goes into more detail about the suggested control methods. A DC-DC converter links the solar source and the load, or grid system. The converter is coupled with either the output load or the external grid via a resistor to guarantee that the system is adequately stable. The planned system can be operated at any load percentage depending on the power need at the system's load end. Since the voltage is constantly maintained constant, this is achieved by controlling the current necessary to satisfy the given power demand.

A. Droop Control In Dc Networks

In a DC system, a droop control is employed as the guiding principle to parallel the converters. keep the right balance of power between them. The error that occurs is removed by the droop controller, in preserving the system's rated constant voltage. Droop management is possible.

In many ways. Droop is typically regarded as a delay or reduction in the necessary voltage at a specific point in time. Typically, the delay or loss from the rated voltage is considered the error signal that is sent in order to create the feedback signal and the duty cycle signal for the converter's switch. When the external voltage is lower, the error signal is produced. beyond what is necessary to satisfy the converters' standards, such as the output voltage or the rated voltage. In a different approach, the feedback signal is produced by a voltage droop controller, which employs several converter signals as a source and a reference. Droop control techniques are frequently employed in microgrid networks to preserve the rated voltage throughout the grid. Droop control is used to regulate the power distribution between the grid system and the converters. The power provided to control voltage droop, the error between the converters is tracked and the feedback signal is produced taking place in the system. Generating units, energy storage units, and interface components make up microgrids between the grid and the converters. Maintaining an equitable and effective power split is necessary between them for the microgrid system's effective stability. The power exchanged is analysed, calculated, and a function of converter constants and variables is produced. sent to the controller for droop. To generate the error or to generate the mistake or feedback, a reference voltage signal is used as a signal for the controller of droop. Typically, the system's rated voltage serves as the reference.

B. Droop Control For Dc Distribution Systems

The style of the DC microgrids flourished as the use of renewable energy increased sources using photovoltaic generation methods, wind energy generation technologies, improved integrated power systems and DC microgrid installation in island and networked networks. DC microgrids can often function in both islanded and grid-connected modes. The microgrid's grid connected operating mode aids in increasing the reliability of the power supply, increases the efficiency of distributed generators, lessens the effect of erratic power supply, and also raises the quality of the power. To restore the stability of the energy storage units when the microgrid is in islanded mode, the system. Controlling voltage droop is used to the integrated systems connected to the network can be more effectively shared power by microgrid system. Along with the droop control, virtual impedance control is also employed, although the output current must be measured and analyzed by the control method. a converter control feature The output current sensing is eliminated using an output variable. The redesigned droop controller includes the output variables of the converter, which are related to the system's output power.

C. Droop characteristics of DC micro grid

In a DC network, the droop controller is used to keep the voltage constant and regulate the power according to demand. The basic principle is to control the converter's output voltage in order to maintain the desired load power. The output current to the load and to the coupling resistor can be changed, allowing the output power to the grid to be adjusted based on the required load percentage by adjusting the output voltage of the converter. The entire model is built around the idea of keeping the voltage droop to a minimum. The proposed model's droop curve is shown in Fig. 3. The current of the system is shown on the X-axis. The Y-axis represents

the output voltage of the converter viz. V_{DC1} and V_{DC2} .

The parallel voltage regulated module (VRM) application was the first to use the droop control mechanism [22]. The secondary controller contrasts the average detected output current (i_0) with the actual sensed output current (i^*_0) of each VRM. When i_0 is greater than i^*_0 , the comparator simply outputs a voltage correction term; otherwise, it outputs zero. The reference voltage for the primary controller is then created by subtracting the product of the fixed virtual resistance (R) and output current I from the δ_0 reference voltage (V_o^*) and adding the result to the comparator output (V_0), we get:

$$v_{ref}^* = v_o^* - \delta v_o$$

$$\delta v_o = k_p + \frac{k_i}{s}(v_{ref}^* - v_o^*)$$

where, K_p is proportional controller and K_i is integral controller.

Higher output current reduces the effectiveness of this approach, and it is unable to produce excellent voltage regulation across each converter's load.

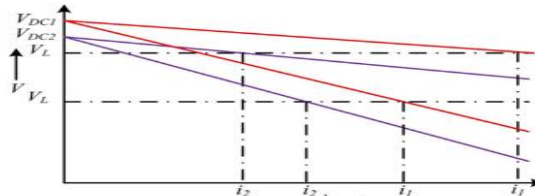


Fig. 3: Droop Characteristics

4. Load Sharing and Circulating Currents Issue

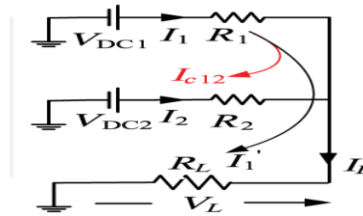


Fig.4 Parallel Equivalent Circuit For The Dc Output Side

Discussions are held regarding problems with parallel dc-dc converters linked to low-voltage dc microgrids. In Fig. 4, two parallel linked dc-dc converters that connect DC grid and PV arrays. The output voltages, output currents, and cable resistances of the devices are represented in this figure as V_{DC1} , V_{DC2} , I_1 , I_2 , and R_1 , R_2 . converters 1 and 2 are designated as Conv-1 and Conv-2, respectively. A voltage source in series with the cable resistance and its equivalent might be used to represent the converter's output side. It displays the circuit [12]. If I_{c12} is the case, $V_{DC1} > V_{DC2}$ Conv-1 to Conv-2's circulating current component, and Case studies for current sharing and circulating current based on the converters output voltages and cable resistances are listed in Table I.

Table 1 Circulating current, output voltages & resistance

Case	V_{DC1}, V_{DC2}	R_1, R_2	I_1, I_2	I_{c12}, I_{c21}
1	Equal	Equal	Equal	Zero
2	Equal	Different	Different	Zero
3	Different	Equal	Different	Not Zero
4	Different	Different	Different	Not Zero

A. Parallel Units Distributed Generators

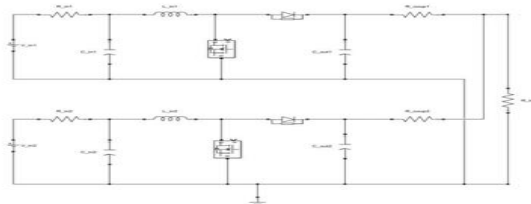


Fig. 5: Equivalent Circuit Diagram of Parallel Units

connections between the load and the output grid are made by two distributed generators. Using the system's droop control, the power sharing between the two generators is managed. In this case, converters 1, 2, and the grid all provide electricity to the load. Even if neither converter operates at full capacity, the overall power demand is distributed between the converters and the grid in an efficient manner. The single unit distributed generator's construction is identical to that

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of the duty cycle and droop controllers. The functioning of the parallel unit is comparable to that of the single unit. The power source for both units is a photovoltaic generating system. To improve power sharing among the converters, the distributed generators are connected in parallel. The converter is used to boost the voltage to the rated value. The controller of both units is set up in such a manner that it can produce the required output power even if one of the units connected in parallel does not operate at full load capacity.

5. Results And Discussions

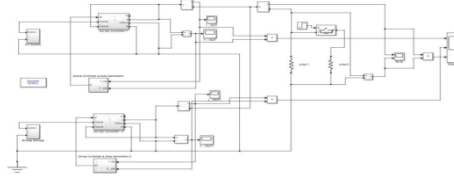


Fig.6: Simulink model of DC Microgrid with droop controller

The droop controller block is built using the derived droop equation as a basis. It generates the signal required for duty cycle generation based on the load demand. The value varies according to changes in output load power. A PWM generator in the duty cycle generator block produces the switching signal for the MOSFET switch. The duty cycle generator block is built using the standard duty cycle equation to avoid system instability issues. The duty cycle is given to the switch in order to facilitate the conversion activity of the boost converter.

A. Droop Controller Block

The fig.7 below shows the droop controller block. The output voltage and current are monitored in the droop controller block. The voltage and current across the load are given as the input to the droop controller. The droop controller is designed based on full load rating and hence the required output current. This block generates the required output voltage for the converter to maintain the rated voltage across the system. The calculated signal is given to a PWM generator for the generation of the duty cycle to be given to the switch connected to the DC-DC converter. The components are made to produce output voltage and power at their rated levels. The proposed system is simulated using MATLAB/Simulink environment. Fig.6 shows the Simulink model.

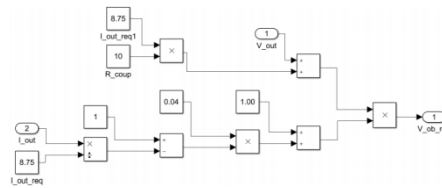


Fig.7. Droop Controller Block

B. Duty Cycle Generator Block

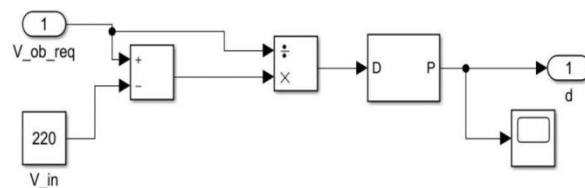


Fig 7. SIMULINK Model of the Duty Cycle Generator Block

In the duty cycle generator block, a PWM generator is used to generate the switching signal for the MOSFET switch. The standard duty cycle equation is used to build the duty cycle generator block to avoid instability issues in the system. The duty cycle is given to the switch to enable the conversion operation of the boost converter. The components are designed to obtain rated values of output voltage and power.

The load and the output grid are both connected in parallel by two distributed generators. The system's droop control is used to regulate how much power is shared between the two generators. The way a parallel unit operates is comparable to how a single unit operates. Here, converters 1, 2, and the grid all share the electricity going to the load. Even if neither converter operates at full capacity, the overall power demand is efficiently split between the converters and the grid. The duty cycle generators and droop controllers are constructed similarly to single unit distributed generators. For the simulation parameters used are depicted in Table II.

Regardless of whether one of the parallel-connected units is not operating at full load capacity, the controller of both units is configured so that it can still generate the appropriate output power. The entire grid system is improved as a result, resulting in constant power delivery to the load. As a result, the system becomes less unstable and there is a lower chance of a blackout since the load power may be efficiently distributed among the converters.

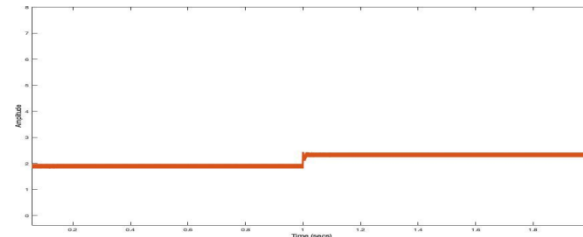
TABLE2:Table to test captions and labels

Sr.No.	Parameter	Rating
1	Source-1&Source-2	$V_{DC1}=V_{DC2}=110V$
2	GridBusvoltage	220V
3	Inductor(L)	1mH
4	Capacitor(C)	1 μF
5	InternalResistances	$R_1=R_2=0.001$
6	Powers	$PL1=800W$ & $PL2=200W$
7	PIController	$K_P=0.025$ & $K_I=1.25$

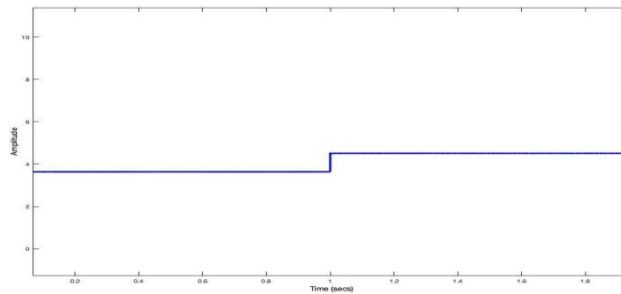
C. Power Sharing

In order to improve the power sharing across the converters, the distributed generators are linked in parallel.

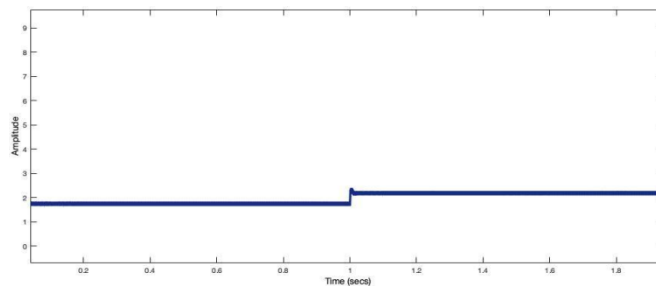
The converter raises the voltage to the specified level. The system's droop control is used to regulate how much power is shared between the two generators. The way a parallel unit operates is comparable to how a single unit operates. Here, converters 1, 2, and the grid all share the electricity going to the load. Even if neither converter operates at full capacity, the overall power demand is efficiently split between the converters and the grid. The duty cycle generators and droop controllers are constructed similarly to single unit distributed generators. Here, to demonstrate equal power sharing two cases are considered. Case 1 is considered to have a power of 800W; whereas case 2 is of 1000W (200W increased). The simulation results show that current is equally shared without burdening the converter or source, as shown in Fig. 8. From Fig. 9, it is seen that both converters will share equally, and during this time the bus voltage will be maintained at rated values. The output power of both converters and load power is also verified using the simulation with the help of aforementioned two cases and the results are shown in Fig. 1



(a) IDC1



(b) IDC2



(c) IDC

Fig. 8: Current waveform for converter 1 & converter-2 and load

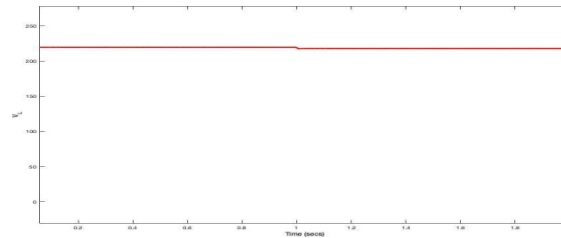


Fig. 9 : Load voltage during case-1 ($PL1 = 800W$) and case-2 ($PL2 = 1000W$)

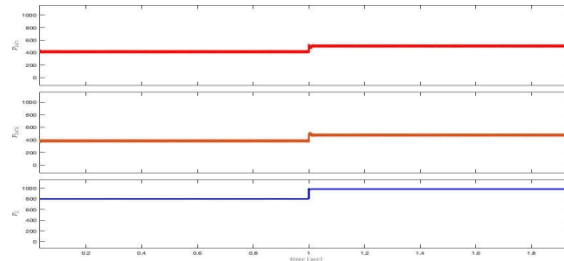


Fig.10 : Output power for case-1 ($PL1 = 800W$), case-2 ($PL2 = 1000W$) and load power

6.Conclusion

The proposed system uses droop control to regulate how much power is shared between the two generators. The way a parallel unit operates is comparable to how a single unit operates. Here, converters 1, 2, and the grid all share the electricity going to the load. Even if neither converter operates at full capacity, the overall power demand is efficiently split between the converters and the grid. The duty cycle generators and droop controllers are constructed similarly to single unit distributed generators. The simulation results demonstrate that the power is shared equally. Furthermore, it is seen that there is no burden on either of the converters, and equal sharing is done by both converters even after there is a change in load. This proposed system can be further designed and developed using advanced controllers to improve transient stability. Future work will concentrate on increasing the number of converters in the system, examining how well it performs when power is shared, and using alternative renewable energy sources as the main energy source for various distributed generator systems. To evaluate the system's effectiveness and efficiency, the proposed model's hardware implementation must also be used..

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